

# Quantum Mechanics A

## Solutions

### Problem Set 4.

#### Problem 1

First, we will need the following general integration

$$\begin{aligned}
 I_{\alpha, \beta}(\vec{r}_a, \vec{r}_b) &= \int d^3r_M e^{-\alpha(\vec{r}_a - \vec{r}_M)^2} e^{-\beta(\vec{r}_M - \vec{r}_b)^2} \\
 &= e^{-(\alpha r_a^2 + \beta r_b^2)} \int d^3r_M e^{-(\alpha + \beta) \left[ r_M^2 - 2 \frac{(\alpha \vec{r}_a + \beta \vec{r}_b) \cdot \vec{r}_M}{\alpha + \beta} \right]}
 \end{aligned}$$

in order to do this, we need to complete the square as follows

$$I_{\alpha, \beta}(\vec{r}_a, \vec{r}_b) = e^{-(\alpha r_a^2 + \beta r_b^2)} e^{(\alpha + \beta) \left[ \frac{\alpha \vec{r}_a + \beta \vec{r}_b}{\alpha + \beta} \right]^2} \int d^3r_M e^{-(\alpha + \beta) \left[ r_M - \frac{\alpha \vec{r}_a + \beta \vec{r}_b}{\alpha + \beta} \right]^2}$$

$$I_{\alpha, \beta}(\vec{r}_a, \vec{r}_b) = \left( \frac{\pi}{\alpha + \beta} \right)^{3/2} e^{-\frac{\alpha \beta}{\alpha + \beta} (\vec{r}_a - \vec{r}_b)^2}$$

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-1-

We are going to use -1- repeatedly:

1) integration over  $\vec{r}_1$

$$\int d\vec{r}_1 e^{\frac{i}{2} \frac{m}{\hbar \Delta t} (\vec{r}_0 - \vec{r}_1)^2} e^{\frac{i}{2} \frac{m}{\hbar \Delta t} (\vec{r}_1 - \vec{r}_2)^2}$$

In this case  $\alpha = \beta = -\frac{i m}{2 \hbar \Delta t} = \Im$

The result is

$$\left(\frac{\pi}{2\Im}\right)^{3/2} e^{-\frac{\Im}{2} (\vec{r}_0 - \vec{r}_2)^2}$$

2) integration over  $\vec{r}_2$

$$\int d\vec{r}_2 e^{-\frac{\Im}{2} (\vec{r}_0 - \vec{r}_2)^2} e^{-\Im (\vec{r}_2 - \vec{r}_3)^2}$$

$$= \left(\frac{\pi}{\frac{\Im}{2} + \Im}\right)^{3/2} e^{-\frac{\Im(\frac{3}{2})}{\Im + \frac{3}{2}} (\vec{r}_0 - \vec{r}_3)^2}$$

$$= \left(\frac{2\pi}{3\Im}\right)^{3/2} e^{-\frac{\Im}{3} (\vec{r}_0 - \vec{r}_3)^2}$$

3) Integration over  $\vec{r}_3$  gives

$$\left(\frac{3\pi}{4S}\right)^{3/2} e^{-\frac{3}{4}(\vec{r}_0 - \vec{r}_4)^2}$$

...

N) Integration over  $\vec{r}_N$  gives.

$$\left(\frac{N\pi}{(N+1)S}\right)^{3/2} e^{-\frac{3}{N+1}(\vec{r}_0 - \vec{r}_f)^2}$$

Including all prefactor we have

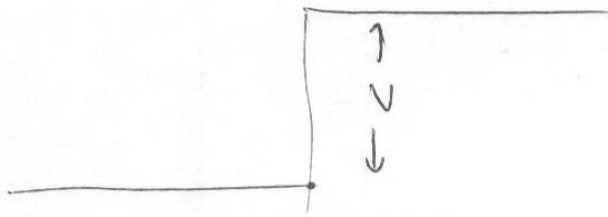
$$\begin{aligned}
 & C \left( \frac{\pi}{2S} \frac{2\pi}{3S} \frac{3\pi}{4S} \dots \frac{N\pi}{(N+1)S} \right)^{3/2} e^{\frac{i m}{2\hbar \Delta t (N+1)} (\vec{r}_0 - \vec{r}_f)^2} \\
 &= C \left( \frac{\pi}{S} \right)^{3N/2} \left( \frac{1}{N+1} \right)^{3/2} e^{\frac{i m}{2\hbar} \frac{(\vec{r}_0 - \vec{r}_f)^2}{t_f - t_0}} \\
 &= C \left( \frac{\pi}{S} \right)^{\frac{3(N+1)}{2}} \left( \frac{S}{\pi(N+1)} \right)^{3/2} e^{\frac{i m}{2\hbar} \frac{(\vec{r}_0 - \vec{r}_f)^2}{t_f - t_0}} \\
 &= \left( \frac{m}{2\pi i \hbar \Delta t} \frac{-\pi 2\hbar \Delta t}{i m} \right)^{\frac{3(N+1)}{2}} \left( \frac{-i m}{2\hbar \Delta t \pi(N+1)} \right)^{3/2} e^{\frac{i m}{2\hbar} \frac{(\vec{r}_0 - \vec{r}_f)^2}{t_f - t_0}}
 \end{aligned}$$

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$$= \left( \frac{m}{2\hbar i \pi (t_f - t_0)} \right)^{3/2} e^{\frac{i m}{2\hbar} \frac{(\vec{r}_0 - \vec{r}_f)^2}{t_f - t_0}}$$

and we have used the fact that  $t_f - t_0 = (N+1)\Delta t$ .

## Problem 2



The incident wave packet @  $t=0$  has a wave function of the form

$$\psi_{inc}(x, t=0) = \int \frac{dp}{2\pi\hbar} f(p) e^{\frac{i}{\hbar} p x} e^{-\frac{i}{\hbar} E_p t} \Big|_{t=0} \quad (2.1)$$

The reflected wave packet @  $t=0$  has a wave function of the following

$$\psi_{ref}(x, t=0) = \int \frac{dp}{2\pi\hbar} f(p) \left( \frac{p - \bar{p}}{p + \bar{p}} \right) e^{\frac{i}{\hbar} (-p x - E t)} \Big|_{t=0}$$

however, as discussed in class

$$\frac{p - \bar{p}}{p + \bar{p}} = -e^{i2\delta} = e^{i[2\delta + \pi]}$$

where

$$\tan \delta = \frac{p}{\hbar k} = \sqrt{\frac{E}{V-E}}$$

Therefore

$$\psi_{\text{refl}}(x, t) = \int \frac{dp}{2\pi\hbar} f(p) e^{\frac{i}{\hbar}(-px + (2\delta + \pi)\hbar - E_p t)}$$

For a wave packet with  $f(p)$  peaked around some  $p = p_0$  or for a single well-defined momentum  $p = p_0$  we can write this as

$$\psi_{\text{refl}}(x, t) = \int \frac{dp}{2\pi\hbar} f(p) e^{\frac{i}{\hbar}(-p(x - x_0) - E_p t)} \quad (2.2)$$

where

$$x_0 = \frac{(2\delta + \pi)\hbar}{p_0}$$

by comparing (2.2) and (2.1) we find that

$$\psi_{\text{reflected}}(x, t) = \psi_{\text{incident}}(-x + x_0, t)$$

However, if the process of reflection, were instantaneous we would have had

$$\psi_{\text{refl}}(x, t) = \psi_{\text{inc}}(-x, t)$$

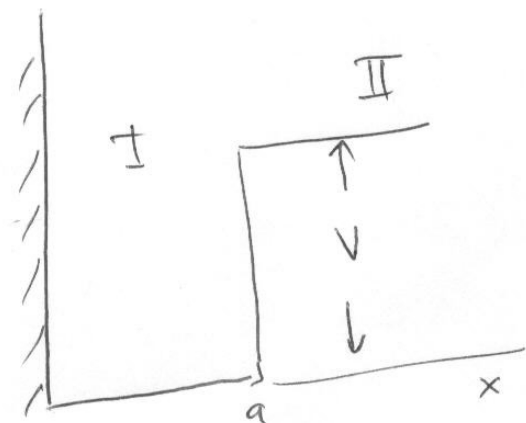
Thus there is a distance of travel within the step of size  $x_0 = \frac{(2\delta + \eta)\hbar}{p}$

Similarly we could write

$$\psi_{\text{refl}}(x, t) = \int \frac{dp}{2\pi\hbar} f(p) e^{\frac{i}{\hbar}(-px - E_p(t - t_0))}$$

where  $t_0 = \frac{(2\delta + \eta)\hbar}{E_p}$

Problem 3



a) 
$$\psi(x) = \begin{cases} A \sin kx, & 0 < x < a, \quad k = \frac{\sqrt{2mE}}{\hbar} \\ B e^{-\bar{k}x}, & x > a, \quad \bar{k} = \frac{\sqrt{2m(V-E)}}{\hbar} \end{cases}$$

Boundary Conditions

$$\psi_I(a) = \psi_{II}(a) \Rightarrow A \sin ka = B e^{-\bar{k}a} \quad (3.1)$$

$$\psi'_I(a) = \psi'_{II}(a) \Rightarrow A k \cos ka = -\bar{k} B e^{-\bar{k}a} \quad (3.2)$$

dividing (3.2) by (3.1) we obtain

$$\bar{k} \tan ka = -k \quad (3.3)$$

(b) Eq. 3.2 can be written in terms of  $k$  as follows:

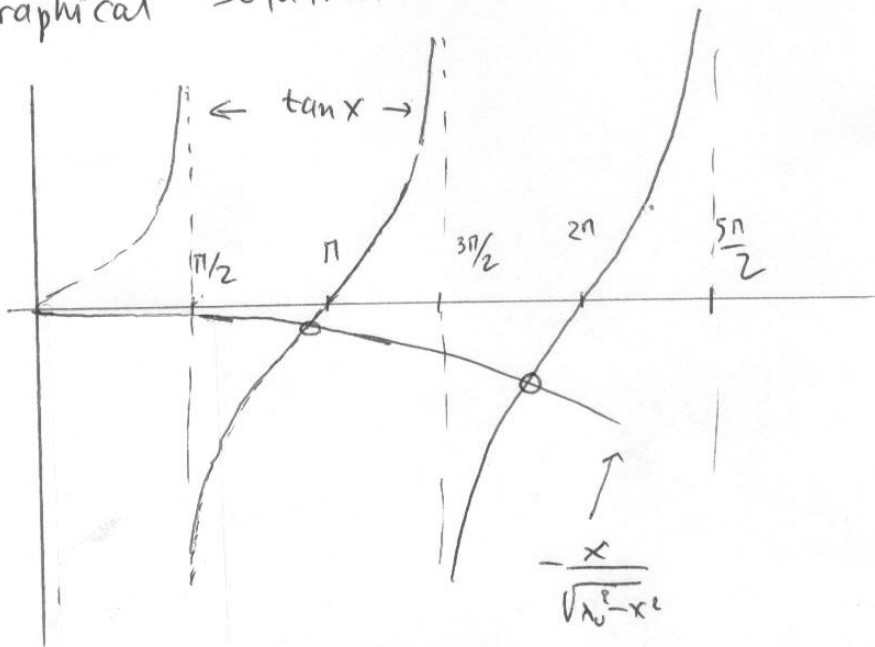
$$\tan ka = - \frac{ka}{\sqrt{\lambda_0^2 - (ka)^2}} \quad (3.4)$$

where  $\lambda_0^2 = \frac{2mVa^2}{\hbar^2}$

Let's call  $x = ka$ , then

$$\tan x = - \frac{x}{\sqrt{\lambda_0^2 - x^2}} \quad (3.5)$$

Graphical solution





c) For large  $V$   $\lambda_0$  is large  
and

$$-\frac{x}{\sqrt{\lambda_0^2 - x^2}} \approx -\frac{x}{\lambda_0} \quad \text{for } \frac{x}{\lambda_0} \text{ small}$$

In this case the intersection is just below  $\pi$ .

i.e

$$x \approx \pi - \varepsilon \quad \varepsilon \rightarrow 0^+$$

and

$$\tan x = -\tan \varepsilon \approx -\varepsilon$$

and in order to determine  $\varepsilon$  we can use  
(3.5) as follows:

$$-\varepsilon = -\frac{\pi - \varepsilon}{\sqrt{\lambda_0^2 - (\pi - \varepsilon)^2}}$$

we need to expand the rhs in power of  $\varepsilon$   
and we find that

$$\text{rhs} = -\frac{\pi}{\sqrt{\lambda_0^2 - \pi^2}} + \frac{\varepsilon}{\sqrt{\lambda_0^2 - \pi^2}} + o(\varepsilon^2)$$

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which implies that

$$\epsilon \approx \frac{\pi}{1 + \sqrt{\lambda_0^2 - a^2}} \stackrel{\text{lim } \lambda_0 \gg 1}{\approx} \frac{\pi}{\lambda_0} = \frac{\pi \hbar}{\sqrt{2mV} a}$$

d) we need to normalize  $\psi$  as follows

$$\int_0^{\infty} |\psi(x)|^2 dx = 1 \Rightarrow \int_0^a |\psi(x)|^2 dx + \int_a^{\infty} |\psi(x)|^2 dx = 1$$
$$\Rightarrow |A|^2 \int_0^a \sin^2 kx dx + |B|^2 \int_a^{\infty} e^{-2kx} dx = 1$$

$$|A|^2 \left[ \frac{a}{2} - \frac{1}{4k} \sin 2ka \right] + |B|^2 \frac{e^{-2ka}}{2k} = 1$$

using eq. 3.1 we can write

$$|B|^2 \left[ \frac{e^{-2ka}}{2k} + e^{-2ka} \left( \frac{a}{2} - \frac{1}{4k} \sin 2ka \right) \right] = 1$$

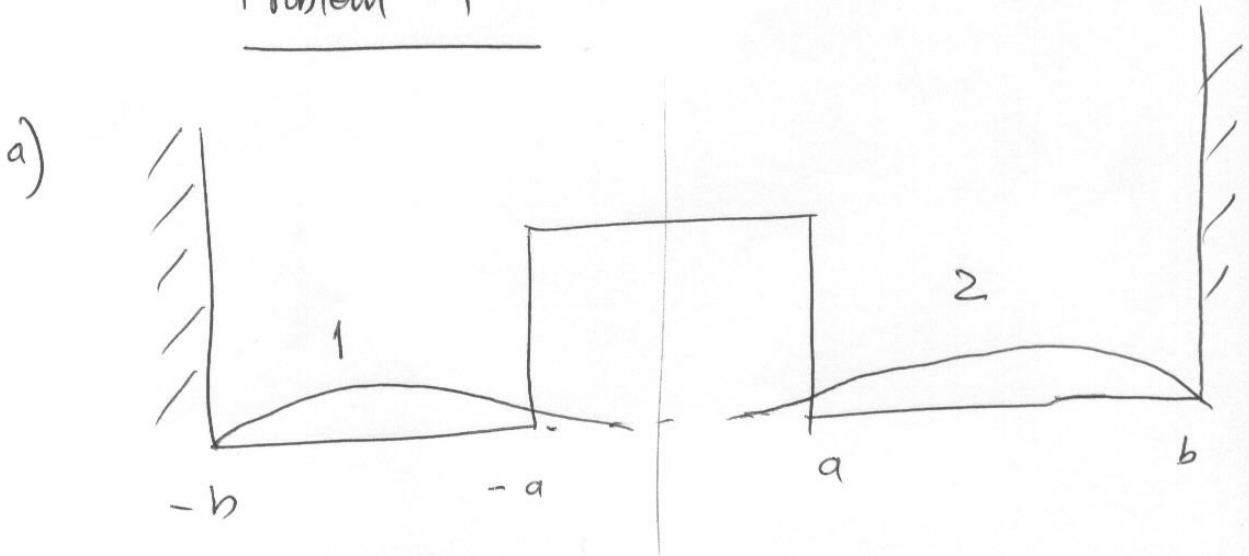
The first term is small in the large  $V$  limit

$$\text{Therefore } |B|^2 \approx e^{2ka} \frac{2}{a} \frac{1}{1 - \frac{\sin 2ka}{2ka}}$$

Thus

$$\psi(x > a) \approx \sqrt{\frac{2}{a}} \frac{1}{\sqrt{1 - \frac{\sin 2ka}{2ka}}} e^{-k(x-a)}$$

Problem 4



$$\psi_1(x) = \begin{cases} A \sin k(x+h) & a < |x| < b \\ B e^{-k(x+h)} & |x| < a \end{cases}$$

in addition  $A$  and  $B$  are related to those of the previous problem by replacing  $a$  with  $(b-a)$ .

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$$\psi_2(x) = \begin{cases} A \sin[k(-x+b)] & a < |x| < b \\ B e^{-\bar{k}(-x+b)} & |x| > a \end{cases}$$

namely  $\psi_2(x) = \psi_1(-x)$  (it is the mirror image of  $\psi_1$ ).

$$b) \quad h_{11} = \int dx \psi_1^*(x) H \psi_1(x) \approx E$$

where  $E$  is the ground state of the left problem.

$$h_{22} = \int dx \psi_2^*(x) H \psi_2(x) \approx E$$

$$h_{12} = \int dx \psi_1^*(x) H \psi_2(x) = E \int dx \psi_1^*(x) \psi_2(x)$$
$$\approx E |B|^2 \int_{-a}^a e^{-\bar{k}(x+b)} e^{-\bar{k}(-x+b)} dx =$$

$$= 2a E |B|^2 e^{-2\bar{k}b}$$

c) Therefore, the matrix is

$$\begin{pmatrix} E & 2aE|B|^2 e^{-2\bar{k}b} \\ 2aE|B|^2 e^{-2\bar{k}b} & E \end{pmatrix} =$$

$$E \begin{pmatrix} 1 & \alpha \\ \alpha & E \end{pmatrix} \quad \text{where } \alpha = 2a|B|^2 e^{-2\bar{k}b}$$

The eigenvalues of this are

$E(1 \pm \alpha)$  and the corresponding eigenstates,

$$\psi_{\pm}(x) = \frac{1}{\sqrt{2}} (\psi_1 \mp \psi_2) = \frac{1}{\sqrt{2}} (|1+\rangle \mp |1-\rangle)$$

d) The initial state can be expressed in terms of the two eigenstates as follows:

$$|1+\rangle = \frac{1}{\sqrt{2}} (|1+\rangle + |1-\rangle)$$

Therefore, the initial state can be written as follows

$$|\psi(t=0)\rangle = |1\rangle = \frac{1}{\sqrt{2}} (|+\rangle + |-\rangle)$$

where  $|+\rangle$  and  $|-\rangle$  are the eigenstates of  $H$ . Thus, at time  $t > 0$

$$\begin{aligned} |\psi(t > 0)\rangle &= \frac{1}{\sqrt{2}} \left[ e^{-\frac{i}{\hbar} E_+ t} |+\rangle + e^{-\frac{i}{\hbar} E_- t} |-\rangle \right] \\ &= \frac{1}{\sqrt{2}} e^{-\frac{i}{\hbar} E t} \left( e^{\frac{i}{\hbar} E \alpha t} |+\rangle + e^{\frac{i}{\hbar} E \alpha t} |-\rangle \right) \end{aligned}$$

The amplitude to go to state  $|2\rangle$  at time  $t$  is given by the inner product:

$$\langle 2 | \psi(t > 0) \rangle$$

and  $|2\rangle = \frac{1}{\sqrt{2}} (|+\rangle - |-\rangle)$

Thus,

$$\langle 2 | \psi(t) \rangle = \frac{1}{2} \left( e^{-\frac{i}{\hbar} E \alpha t} - e^{\frac{i}{\hbar} E \alpha t} \right) = -i \sin(E \alpha t)$$

The probability is

$$|\langle z | \psi(t) \rangle|^2 = \sin^2(E\alpha t)$$

where

$E, \alpha$  have been defined earlier,